

# Iterated learning of vowel harmony with Bayesian agents

*DGfS AG4: “Learning Meets Acquisition”*

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# Overview

- 1 Motivation & Background
  - Explanation in phonology
  - VH, Phonologization & Coarticulation
  - Modelling language change
- 2 Modelling the emergence of harmony
  - The agent
  - The algorithm
- 3 Results & Discussion
  - Next steps

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# Diachronic explanation of synchronic patterns

Increasing push away from synchronic, grammar-based<sup>1</sup> explanations, toward diachronic, phonetic accounts of phonological patterns (cf. Blevins 2004, Hale & Reiss 2007, Ohala 1992, 2005 *inter alia*).

- ① reduce implausible teleological aspects of phonological explanation (cf. Zipf 1935)
- ② Ockham's Razor (i.e. eliminate explanatory redundancy)
- ③ ease Mother Nature's burden (e.g. how to evolve a complex UG)

Focus on a particular case here: the development/emergence of *vowel harmony*.

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<sup>1</sup>Esp. markedness-based

## Q: Where does vowel harmony come from?

John Ohala (1994) provided the standard (but not universally accepted) answer:

*Vowel harmony is a result of the phonologization of vowel-to-vowel coarticulation.*

**Is there any way of verifying this type of claim?**

# Linguistic background in a nutshell

**Vowel harmony** To a first approximation, vowels in some domain (“the word”) agree with respect to some set of phonological features, both as a lexical generalization, and w.r.t. productive alternations (e.g. Finnish backness harmony)

**Phonologization** *A universal phonetic tendency is said to become “phonologized” when language specific reference must be made to it, as in a phonological rule. (Hyman 1972:170) [...] phonologization, whereby a phonetic process becomes phonological. . . (Hyman 1975:171)* Variation under physical/physiological control comes to be under cognitive control.

**Coarticulation** The predictable effects on segments of their neighbours in running speech. e.g. the relative frontness/backness of [k] in *keep* vs. *coop*. V-to-V coarticulation occurs across intervening consonants (cf. Öhman 1966, Magen 1997 *inter alia*), and is perceivable by listeners (Beddor et al. 2002).

# Sidebar: criteria for VH?

How do we decide whether a language “has” vowel harmony?

- ① lexical statistics
  - (e.g. deviance from expected rate of harmony, given vowel inventory)
- ② loanword adaptation
  - (e.g. “harmonization” of disharmonic borrowings)
- ③ synchronic alternations
  - (e.g. as in Finnish suffixes above)

I will focus mostly on (i) and a little bit on (ii) here.

# Diachronic explanation . . .

For a candidate explanation of this type, we need:

- ① demonstrable synchronic variation
- ② proof that variation is detectable by listeners
- ③ models of synchronic knowledge and acquisition
- ④ *a demonstration that the above + sufficient time can bring about the phenomenon under consideration*

Point 4 runs into problems.



# A methodological stumbling block

- No obvious way to verify the diachronic aspect of this kind of explanation
- Modelling gives us a “virtual lab” in which to test these theories, with perfect repeatability and tight control over parameters
- Other benefits of modelling: (i) quantitative data allow theory comparison/choice, (ii) implementation forces us to be very precise about our theory, parameters and auxiliary assumptions

# Modelling language change

- Computational/mathematical modelling of language change is (with few exceptions *cf.* Klein 1969) a relatively recent development in linguistics (~10 years).
- Mostly deals with syntactic change, with some work on morphological change. Little work on phonological change until quite recently.
- Modelling strategies can be classified as *analytic* (equation-based) (*cf.* Niyogi & Berwick 1995 *et seq.*, Komarova & Nowak 2003) or *synthetic* (agent-based).

# Synthetic models

A.K.A. *agent-based modelling, multi-agent simulation*

- Individuals explicitly modeled, population-level properties emerge from local interactions.
- Agents have perception/comprehension model, production model, and internal state/grammar)
- Internal state changes on basis of agent-to-agent interaction.

Can be further subclassified as *vertical* or *horizontal* according to information flow.

# Agent-based simulation

Vertical information flow: ***iterated learning model*** (Kirby 1999, *et seq.*):

- Typically 2 disjoint subsets of agents, one with fixed internal model (“adults”) and one modifiable (“children”).<sup>2</sup>
- “Adult” grammars serve as targets. Meant to explicitly capture I-/E-language feedback loop in transmission/acquisition.
- Noisy transmission (and/or information bottleneck) drives change.

My model: simplest possible—one adult, one child per generation

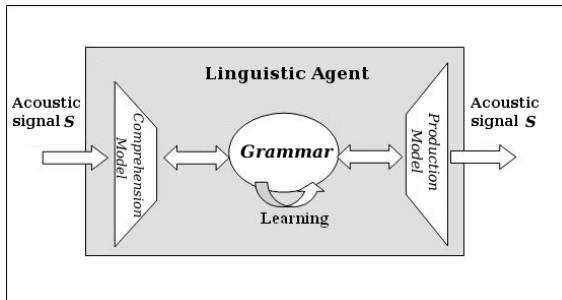
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<sup>2</sup>Horizontal info flow: all agents can change internal state, no privileged grammar(s). “Social” vs. “generational” models.

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# The agent



# The agent

**Mental model:** 2 binary features (“high” and “back”). Words are sequences of 4 vowels. Exhaustive (*i.e.* 256-word) lexicon. No morphophonology (yet!).

## Production model:

- Continuous articulation: binary features transduced to continuous articulatory parameters; beta-distribution models hyper-/hypoarticulation
- Articulatory synthesizer: equations from de Boer (2000) to generate formant values ( $F1$ ,  $F2$ ) from articulatory description
- V-to-V coarticulation: contextual variation in  $F2$  (approx. analogue of front/back variation)

# The agent (cont.)

## Comprehension/learning model:

- Acoustic clustering:  $k$ -means analysis to find acoustic prototypes (GMM-EM too slow, and doesn't reliably find clusters, since data is non-Gaussian)
- Invert articulation-acoustics mapping (this is unrealistic?)
- Feature induction: MAP learning<sup>3</sup> of vowel features from articulatory representations of acoustic prototypes:

$$\hat{h} = \arg \max_h \frac{P(D = d | H = h)P(H = h)}{Z}$$

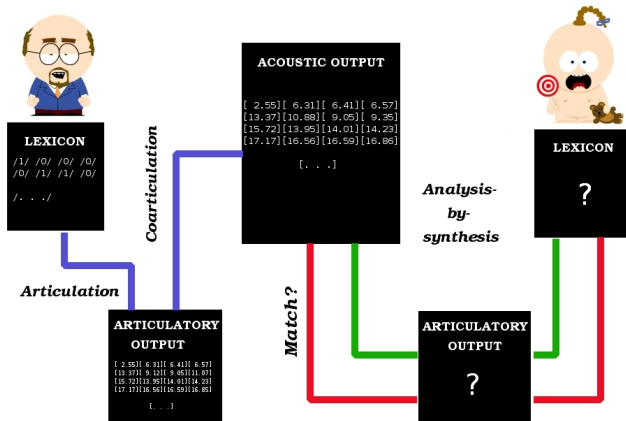
- UR induction: Assign URs to words by vector quantization

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<sup>3</sup>Only uniform priors implemented for now, so this is MLE, strictly speaking.



# Information flow



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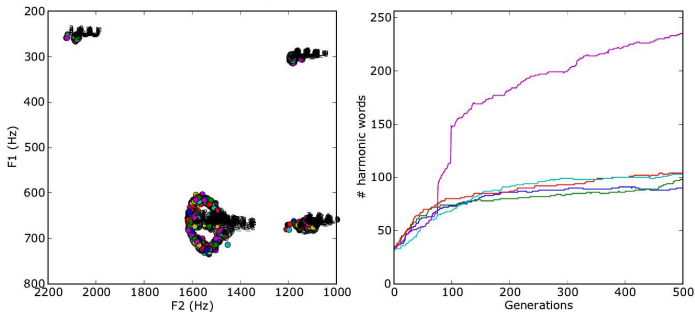
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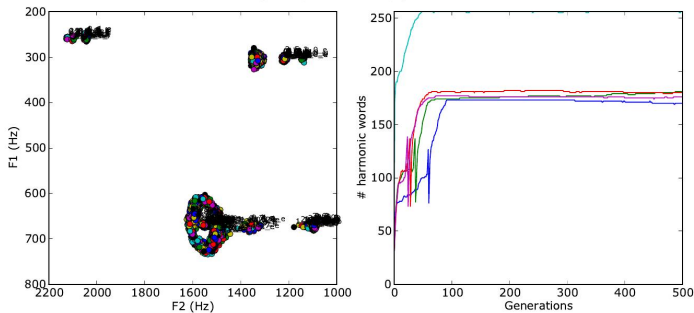
# 500 generations, antic=100

5 agents, antic=100, persev=0



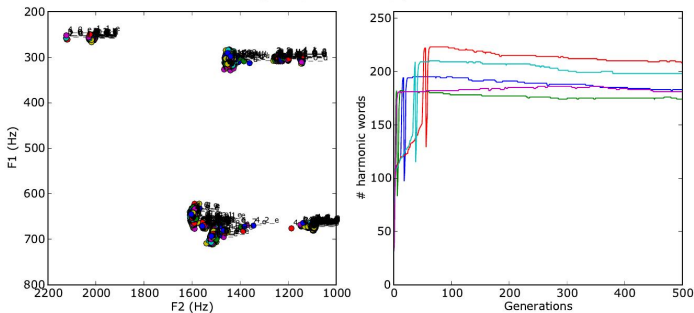
# 500 generations, antic = 200

5 agents, antic=200, persev=0



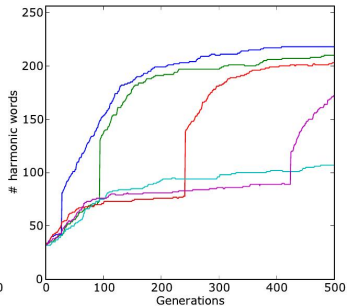
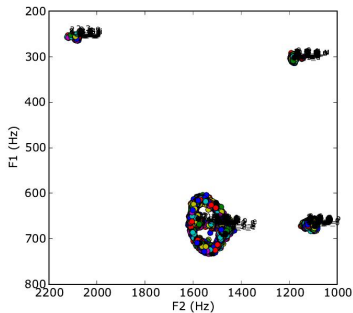
# 500 generations, antic = 300

5 agents, antic=300, persev=0



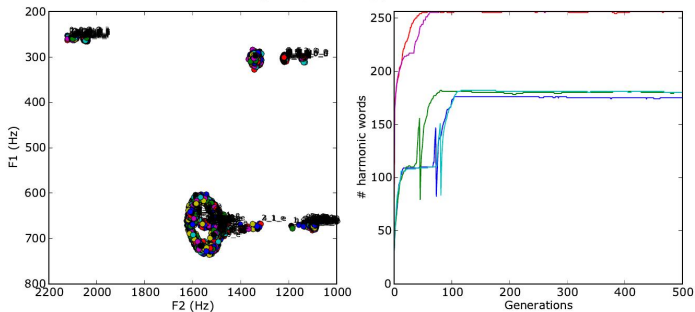
# 500 generations, persev=100

5 agents, antic=0, persev=100



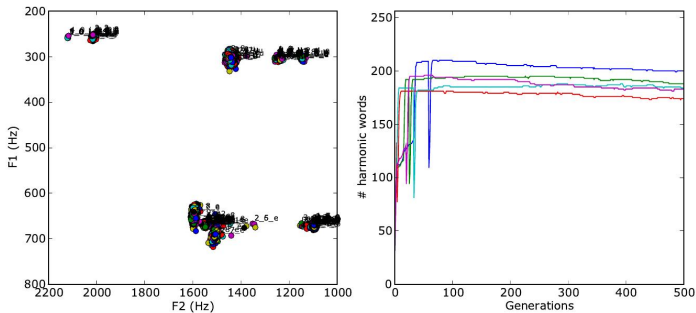
# 500 generations, persev = 200

5 agents, antic=0, persev=200



# 500 generations, persev = 300

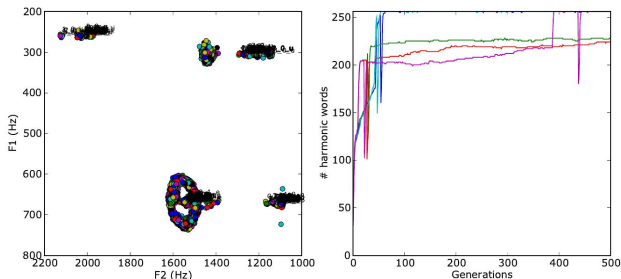
5 agents, antic=0, persev=300



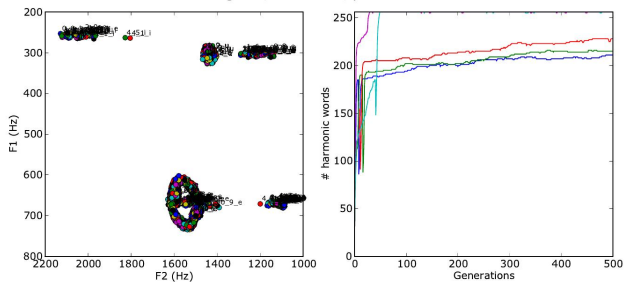


# 500 generations, antic & persev

5 agents, antic=100, persev=300



5 agents, antic=300, persev=100



# Discussion

- Multiple relatively stable levels of harmony, with different approach speeds depending on amount of coarticulation.
- Explainable by differential resistance to coarticulation (maybe just different distance in vowel-space for fixed coarticulation)
- Noisy sets show possible partial solution to actuation problem. . . phonologization need not lead inexorably to harmony

Also, informal tests, show that disharmonic loanwords (i.e. acoustic forms corresponding to disharmonic URs) are typically harmonized by agents with harmonic (approx > 200) lexicons.

# To do

- MAP learning of words
- Morphophonological alternations
- More realistic data (e.g. stochastic sampling of lexicon at each gen?)
- Social factors (variation in data due to multiple independent input sources)
- Exemplar-based approach—embodying very different assumptions about acquisition and change—is next on the agenda.

# Fin

# THANK YOU.<sup>4</sup>

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<sup>4</sup>Thanks to Ash Asudeh, Jeff Mielke, Lev Blumenfeld and various audiences.

# References

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